

HiWind 2024 Structural Analysis

Andrew Carlile

4/30/2024

A substantial change was made in February 2024. Changes to the FEA Upper Gondola analysis were: adding the tri-plate, adding all the panels, changing the Margin of Safety Calculation, and an update to the dummy masses including their shape and not just the mass override. In March 2024 the dummy mass models were removed and replaced by remote masses. The total masses were increased slightly. The Starlink antennae estimate was added, and the results are below.

Drawing Requirements

1. Drawings shall show the relative locations and dimensions of all structural and load-bearing gondola members



The observatory viewports need to be considered keep out zones for NASA and HAO. Clearance between the baffle tube and other structures should be 6 inch away from the ends of the four baffle tubes and 10 inch behind the ends to avoid scattering light. Dimensions in inches.









Model Motion Study 1 * Case 18g Vertical * Case 2 4g 30 Deg to Cable * Case 3a 4g 45 Deg to Side * Case 3b 4g 45 Deg to Angle * Case 4 4g Side Load

	from center of origin in the UGA model					
Mass Description	X [mm]	Y [mm]	Z [mm]	Mass [kg]		
Model including Lower Gondola and Antennaes				1677		
Lower Gondola	0	0	2423	1045.4		
Batteries added into Lower Gondola				150		
Radiator Total	0	-1000	-1500	56		
Makeup Gas	-500	-250	-1500	30		
Radiator Side Panel	0	-1800	-2000	40		
Left Panel	-2200	0	-2000	40		
Right Panel	2200	0	-2000	40		
Front Panel	0	1800	-2000	40		
Starlink	attached					
Total Antennae on Both Faces of tube				60		
total HiWind including remote masses	total HiWir	nd	kg	1923		

2. Drawings shall identify all the materials used for the construction depicted by the drawing

The tubes are aluminum, with Kee Clamp cast iron for the clamps and connections. The upper gondola is mild steel, and all of the hardware is at least grade 8 steel.

3. Material specifications shall be included in all drawings

All parts in FEA are of one of these 3 materials. The steel cable estimate is described in section 6.

Material Properties							
Aluminum 6061 Pu	310	MPa					
Aluminum 6061 Py	276	MPa					
Aluminum 6061-T6; 60	<u>)61-T651 (n</u>	natweb.c	:om)				
Cast Iron Pu	344	MPa					
Cast Iron Py	276	MPa					
https://www.matweb	.com/searc	h/datash	neet.aspx?ma	tguid=ec56	a89f37f74e	2f867a64b	0f87f1e9d
Steel 4130 Pu	670	MPa					
Steel 4130 Py	435	MPa					
Overview of materials	for Mediur	m Alloy S	teel (matweb	.com)			
Calculated in Wor	kbook						
Calculated in Solid	Morks						

4. At least one complete assembly drawing shall be provided HAO cannot currently provide this.

5. Working drawings and specifications for all purchased and fabricated mechanical components and assemblies that are part of the gondola (e.g., rotators, swivels, turnbuckles, clevises, rings, and universal joints) shall be provided

HAO can provide most of these drawings at a later date.

6. A stress analysis of all major structural members, including decks and ballast attachment points shall be provided and shall identify the boundary conditions, components, equipment, and weights comprising the loads

Upper Gondola Attachment Points and Boundary Conditions

The upper gondola attaches to the balloon with the trapeze. The attachment point to the balloon is modeled as a fixed constraint at the top of the trapeze, shown below.



The manually added connectors, either link connector or spring (cable estimate), are shown below.



Dummy Mass Changes

As of March 2024, the dummy mass models have been changed to remote masses, except for the antennas and lower gondola assembly.



Support Cable Estimation

In order to create the cables as a connection in the FEA model a simple steel model was created with a 3/8" diameter and a 1 N load applied. Then the stiffness value was used to create spring connections in the upper gondola analysis.



440

Specific Heat

Material Damping Ratio

J/(kg·K)

N/A

- 📒 Plain Carbon Steel
- Stainless Steel (ferritic)
- 🚰 Wrought Stainless Steel
- 📳 Iron ×. 🚍 Aluminium Allour

The connection points for the spring connection are shown below:









Tri-plate Attachment Fixed Surfaces and Connections to Trapeze

The tri-plate has been imported using the SW default 6061-T6 material. The top holes are fixed, and the connection to the trapeze is set as a solid pin linking the faces, shown below.



Key details from 820-PG-8700.0.1 Gondola Structural Design Requirements

3.3 Design Limit Loads (DLL)

Gondolas shall be designed so that all load-carrying structural members, joints, connectors, decks, and suspension systems show a *positive* margin of safety (MS > 0.0) when subjected to the design limit loads listed below in Table 2 and the desired design factor(s) of safety given in Table 3. Note: some components can only be shown to have positive MS against ultimate strength (e.g. composites).

Table 2: Design Limit Loads

	Design Limit Loads (DLL) G's					
Structural Flight Hardware	Vertical	45 Deg	Horizontal			
	8	4	4			

NOTE:

Metallic materials with a fracture strain of 5% or less, at worst case temperature limit, shall be considered brittle and an additional factor of 1.5 shall be applied to the Design Limit Loads. That is, the particular element that is fabricated using a brittle material must be able to sustain a 12g vertical load, a 6g load applied at 45 degrees off vertical, and a 6g horizontal load without failure.

3.4 Factors of Safety

Design factors of safety (FS) for the gondola structural components and its suspension system are given in Table 3. The Design FS are based upon the worst-case termination event and historic flight profiles. It is paramount that the gondola design ensures that no scientific equipment, CSBF equipment, or ballast separate from the flight system during any phase of flight operation.

Table 3: Design Factors of Safety

TYPE OF HARDWARE	DESIG	N FACTOR OF SA	AFETY				
	Yield	Ultimate	Proof Test				
Metallic Structures							
Flight Structure - metallic only	1.25	1.4	N/A				
Preloaded Joints	1.25	1.4	N/A				
Fasteners	1.25	1.4	N/A				
Welds	N/A	1.5	1.2				
Suspension Systems							
Wire Rope Cables, Slings, Cable assemblies, Shackles, Turnbuckles, etc.	N/A 1.4		*				
Soft-body Structures							
Slings, Webbing	N/A	2.0	*				
Composite Flight Structure							
Uniform Material	N/A	1.5	1.2				
Bonded Joints/Inserts	N/A	2.0	1.2				
Stability/Buckling							
Stability/Buckling – metallic only	N/A	1.4	N/A				
Stability/Buckling - composite	N/A 1.5		N/A				
Pressure Vessel Systems	Ref: GSFC-STI	D-8009, ANSI/AIAA	A S-080A-2018				
*: based upon NASA review of GP hardware							

3.5 Margins of Safety

The strength of the gondola system shall be demonstrated by showing a positive margin of safety (MS) for individual components and assembly interfaces for the given loading environment when the factors of safety given in Table 3 are applied.

The margins of safety are determined by multiplying the design limit load (or stress) by the appropriate factor of safety and comparing it to either the yield or ultimate material allowable strength as shown in the following equations:

 $MS_u = \frac{P_u}{FS_u P} - 1$

$$MS_y = \frac{P_y}{FS_y P} - 1$$

where

and

FS_u	is the ultimate Factor of Safety
FS_y	is the yield Factor of Safety
Р	is the limit load (or stress) calculated in the analysis
P_u	is the load (or stress) at which material failure will occur
Py	is the load (or stress) at which material yielding will occur
MS_u	is the Margin of Safety against ultimate failure
MS_y	is the Margin of Safety against material yielding

At pre-loaded interfaces, the analysis shall show positive margins for all components which comprise the interface – fittings, bolts, rivets, etc., when subjected to the loads given in Section 3.3 and the margins given in Section 3.4. Fitting analysis of critical components shall meet Section 4.4.2, Certification of Fasteners.

6.1 Load Case 1 8g Vertical

4.2.1 Load Case #1

A load 8 times the weight of the payload applied vertically at the suspension point.

Rationale: Vertical load path for parachute opening shock immediately after termination. Optionally, pin base and apply vertical load.



Figure 2: Load Case #1 - Gondola Vertical Loading

Load Case 1 Lower Gondola



Load Case 1 Upper Gondola



📰 Model | Motion Study 1 | 🌢 Case 1 8g Vertical 🗽 Case 2 4g 30 Deg to Cable | 🦗 Case 3a 4g 45 Deg to Side | 🗞 Case 3b 4g 45 Deg to Angle | 🗞 Case 4 4g Side Load





The KeeClamp joining member has a low FOS, the min FOS from the assembly and the max stress of a node in any part will be used in the Safety Factor calculation. Steel is used in the Margin of Safety calculation as the material, as the fastener taking the load is steel.

Load Case 1 Summary

Case 1	8g Vert	ical							
				From		Maximum		Minimum	
				NASA		From FEA		From FEA	
Upper Gon	ndola								
	MSu	1.11	FSu	1.25	Р	2.54E+02	MPa	1.48	FOS
	MSy	0.22	FSy	1.40	Р	2.54E+02	MPa	1.48	FOS
Lower Gon	ndola								
	MSu	2.92	FSu	1.25	Р	1.37E+02	MPa	1.62	FOS
	MSy	1.27	FSy	1.40	Р	1.37E+02	MPa	1.62	FOS

6.2 Load Case 2 4g Angle to Cable

4.2.2 Load Case #2

For multiple-cable suspension systems, each cable must have an ultimate strength greater than 4 times the weight of the payload divided by the sine of the angle that the cable makes with horizontal ($\alpha > 30$ degrees) in a normal flight configuration.

Rationale: The load path through the gondola are directed through the cables so the loads are analyzed acting through the structure.

Note: In reality, the load would be reacted through the gondola inertia and not the feet. For this reason, failure modes due to tension in the feet are not considered.



Figure 3: Load Case #2 – Gondola Single Cable Loading

Load Case 2 Lower Gondola



Load Case 2 Upper Gondola



Load Case 2 Summary

The upper gondola does not pass this case. The lowest factor of safety is in the triplate.

Case 2	4g 30 C	egree to	Cable						
				From		Maximum		Minimum	
				NASA		From FEA		From FEA	
Upper Gor	ndola								
	MSu	-0.90	FSu	1.25	Р	2.58E+03	MPa	0.11	FOS
	MSy	-0.92	FSy	1.40	Р	2.58E+03	MPa	0.11	FOS
Lower Gor	ndola								
	MSu	5.48	FSu	1.25	Р	8.27E+01	MPa	3.30	FOS
	MSy	2.76	FSy	1.40	Р	8.27E+01	MPa	3.30	FOS

6.3 Load Case 3a,b 4g 45 Degree to Vertical

4.2.3 Load Case #3

A load 4 times the weight of the payload applied at the suspension point and 45 degrees to the vertical. This load factor must be accounted for in the direction perpendicular to the gondola's short side, long side, and in the direction of the major rigid support members at the top of the gondola structure. If flexible cable suspension systems are used, they shall withstand uneven loading caused by cable buckling.

Rationale: Assumes that the gondola rotates 45 degrees descends off-axis during termination and only one or two cables are loaded at parachute opening. It is to assure that the structure and attachments can handle this initial load.

Note: In reality, the load would be reacted through the gondola inertia and not the feet. For this reason, failure modes due to tension in the feet are not considered.



Figure 4: Load Case #3 - Off-Vertical Gondola Loading

Load Case 3a,b Lower Gondola





🔣 🐨 Model | Motion Study 1 | 😺 Case 1 8g Vertical | 🕸 Case 2 4g Angle to Cable | 🕸 Case 3a 45 Deg 4g | 🕸 Case 3b 45 Deg 4g | 💱 Case 4 Deg 4g Side

Load Case 3a Upper Gondola



Model | Motion Study 1 😺 Case 18 g Vertical | 🕸 Case 2 4g 30 Deg to Cable | 🕹 Case 3 4 g 45 Deg to Side | 😵 Case 3 b 4g 45 Deg to Angle | 🗞 Case 4 g Side Load

Load Case 3a Summary

Case 3a 45 Degree to Vertical									
				From		Maximum		Minimum	
				NASA		From FEA		From FEA	
Upper Gor	ndola								
	MSu	-0.93	FSu	1.25	Р	3.67E+03	MPa	0.08	FOS
	MSy	-0.95	FSy	1.40	Р	3.67E+03	MPa	0.08	FOS
Lower Gor	ndola								
	MSu	3.67	FSu	1.25	Р	1.15E+02	MPa	2.30	FOS
	MSy	1.71	FSy	1.40	Р	1.15E+02	MPa	2.30	FOS

Load Case 3b Upper Gondola



Nodel | Motion Study 1 | & Case 18g Vertical | & Case 24g 30 Deg to Cable | & Case 3a 4g 45 Deg to Side | & Case 3b 4g 45 Deg to Angle | & Case 4 4g Side Load



Load Case 3b Summary

Case 3b 45 Degree to Vertical									
				From		Maximum		Minimum	
				NASA		From FEA		From FEA	
Upper Gor	ndola								
	MSu	-0.95	FSu	1.25	Р	5.05E+03	MPa	0.05	FOS
	MSy	-0.96	FSy	1.40	Р	5.05E+03	MPa	0.05	FOS
Lower Gon	ndola								
	MSu	4.63	FSu	1.25	Р	9.52E+01	MPa	2.80	FOS
	MSv	2.26	FSv	1.40	Р	9.52E+01	MPa	2.80	FOS

6.4 Load Case 4 4g Side Load

4.2.4 Load Case #4

A lateral load of 4 times the weight of the payload applied to all components and equipment attached to and/or onboard the gondola structure or any portion of the flight system below the balloon at both principal lateral axes.

Rationale: Assumes that the gondola rotates 90 degrees descends off-axis during termination and inertial side loads are applied to components attached to the structure.

Note: Some components are analyzed individually and some are analyzed as part of the structural model. In non-symmetric situations, 4g is applied in both horizontal axis.



Pin constraints

Figure 5: Load Case #4 - Gondola Lateral Loading

Load Case 4 Lower Gondola



Load Case 4 Upper Gondola



ner er bland Model Motion Study 1 🗽 Case 18g Vertical 🕼 Case 24g 30 Deg to Cable 🕼 Case 3a 4g 45 Deg to Side 🕼 Case 3b 4g 45 Deg to Angle 🔌 Case 44g St

Load Case 4 Summary

Case 4 4g	g Side	Load							
				From		Maximum		Minimum	
				NASA		From FEA		From FEA	
Upper Gondo	la								
	MSu	-0.95	FSu	1.25	Р	5.10E+03	MPa	0.05	FOS
	MSy	-0.96	FSy	1.40	Р	5.10E+03	MPa	0.05	FOS
Lower Gondo	la								
	MSu	4.31	FSu	1.25	Р	1.01E+02	MPa	2.73	FOS
	MSy	2.08	FSy	1.40	Р	1.01E+02	MPa	2.73	FOS

6.5 Load Case 5 1.4x Weight on Flight Hardware

4.2.5 Load Case #5 – Flight Hardware to MGSE Interface Verification

A load 1.4 times the weight of the payload applied independently to the gondola in all three orthogonal directions. The mechanical ground support equipment (MGSE) (cart/casters/stand/etc) interface shall be pinned or fixed depending on the interface design.

Our design files are not capable of supporting this analysis.

Summary of Safety Factor Calculations

The lower gondola meets quite a few of the margin of safety requirements, but the upper gondola only passes load case 1. This gondola overall does not meet the calculated safety requirements in this report, additionally HAO does not have a complete submission.

Case 1	8g Vert	ical							
				From		Maximum		Minimum	
				NASA		From FEA		From FEA	
Upper Gor	ndola								
	MSu	1.11	FSu	1.25	Р	2.54E+02	MPa	1.48	FOS
	MSy	0.22	FSy	1.40	Р	2.54E+02	MPa	1.48	FOS
Lower Gor	ndola								
	MSu	2.92	FSu	1.25	Р	1.37E+02	MPa	1.62	FOS
	MSy	1.27	FSy	1.40	Р	1.37E+02	MPa	1.62	FOS
Case 2	4g 30 D	egree to	Cable						
				From		Maximum		Minimum	
				NASA		From FEA		From FEA	
Upper Gor	ndola								
	MSu	-0.90	FSu	1.25	Р	2.58E+03	MPa	0.11	FOS
	MSv	-0.92	FSv	1.40	P	2.58E+03	MPa	0.11	FOS
Lower Gor	ndola		,				-		
	MSu	5.48	ESu	1.25	P	8.27F+01	MPa	3.30	FOS
	MSv	2.76	FSv	1.40	P	8.27F+01	MPa	3.30	FOS
			,			01272.02			
C		araa ta \	/ortical						
Case 3a	a 45 De	gree to v	ertical						
				From		Maximum		Minimum	
				NASA		From FEA		From FEA	
Upper Gor	ndola								
	MSu	-0.93	FSu	1.25	P	3.67E+03	MPa	0.08	FOS
	MSy	-0.95	FSy	1.40	Р	3.67E+03	MPa	0.08	FOS
Lower Gor	ndola								
	MSu	3.67	FSu	1.25	P	1.15E+02	MPa	2.30	FOS
	MSy	1.71	FSy	1.40	Р	1.15E+02	MPa	2.30	FOS
Case 3	b 45 De	gree to V	/ertical						
				From		Maximum		Minimum	
				NASA		From FEA		From FEA	
Upper Gor	ndola								
	MSu	-0.95	FSu	1.25	Р	5.05E+03	MPa	0.05	FOS
	MSy	-0.96	FSy	1.40	Р	5.05E+03	MPa	0.05	FOS
Lower Gor	ndola								
	MSu	4.63	FSu	1.25	Р	9.52E+01	MPa	2.80	FOS
	MSy	2.26	FSy	1.40	Р	9.52E+01	MPa	2.80	FOS
Case 4	4g Side	Load							
				From		Maximum		Minimum	
				NASA		From FEA		From FEA	
Upper Gor	ndola								
	MSu	-0.95	FSu	1.25	P	5.10E+03	MPa	0.05	FOS
	MSy	-0.96	FSy	1.40	P	5.10E+03	MPa	0.05	FOS
Lower Gor	ndola								
	MSu	4.31	FSu	1.25	P	1.01E+02	MPa	2.73	FOS
	MSy	2.08	FSy	1.40	Р	1.01E+02	MPa	2.73	FOS

Narrative on Analysis Types

The tri-plate being fixed and using the gravity vector load with the dummy masses was used because the inertial relief style of analysis has serious problems meshing and converging on a solution. The high quality mesh never completed an analysis run.

Analysis Errors



Exception code 0xc0000005 thrown at address 0x1405f7612.

Please send crash data file Z:\2023 Final FEA Design and Analysis\SIMSTACK-V32,5,0,13-240222-135014.dmpl is under such a force

or under marginally imbalance forces, application of Inertia

Relief may alter the characteristics of your model.

Would you like to continue? "Yes" to SOLIDWORKS technical support. Please press OK to terminate solution Warning: There is a significant external imbalanced force in Z-direction which will be balanced by the application of opposing inertia forces. Unless your model is under such a force or under marginally imbalance forces, application of Inertia Relief may alter the characteristics of your model. Would you like to continue?

7. For critical or single-point failure items material certifications shall be provided in accordance with Section 4.4, Material Requirements for Critical Hardware **To be submitted at a later date**.

8. A statement certifying that the aforementioned requirements have been met; the statement shall be signed by the principal investigator and the engineer responsible for the design and analysis of the gondola structure. Qualifications of the engineer responsible shall be submitted in the form of a brief résumé

HAO cannot provide a statement saying these requirements have been met because they are **not**. Only Load Case 1 is acceptable.

Andrew Carlile

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LinkedIn Profile: https://www.linkedin.com	m/pub/andrew-carlile/28/	b86/159
EDUCATION		
Georgia Institute of Technology		Atlanta, GA
Master of Science Mechanical Engineering	GPA 3.25	May 2015
University of Oklahoma		Norman, OK
Bachelor of Science Aerospace Engineering	GPA 3.33	May 2011
Minor in Mathematics, Cum Laude Honors Graduate		-
Passed FE Exam 2011		
University of Arizona		Online
Master's Certificate Optical Science	GPA 3.4	May 2023

DESIGN, ANALYSIS, AND MANUFACTURING SKILLS Professional experience with: <u>Dassault</u>: SolidWorks and Enovia <u>Autodesk</u>: Inventor, Fusion, and Vault <u>PTC</u>: Creo <u>Zemax</u>: Optic Studio Programming In: MATLAB M-Files, C (Visual Studio), C# (Visual Studio), C++, Beckhoff <u>TwingAT</u>, LaView Simulation experience with: NSYS Workbench, ANYSY CFX, Dymola, Autodesk Inventor Simulation, SolidWorks EEA and Flow Simulation Electronics design, sensor integration, motion control, control, and safety systems, primarily in SolidWorks electrical

- Designed composite parts, machined parts, additive manufactured parts Part documentation, tolerance analysis, and manufacturing planning (Design for Assembly, Design for Manufacturing), System layout and assembly experience
- RESEARCH
- Water Risk Analyses and Strategies for Automotive Manufacturing." Thesis for Master's research, research on sustainable manufacturing, in particular water and energy u
- "Comparison of Water Strategy Tools for Automotive Manufacturing." Society of Automotive Engineers_SAE Paper: 2014-01-1958
- Bublished 04/01/2014
 "The Visible Spectro-Polarimeter of the Daniel K. Inouye Solar Telescope." Solar Physics, de Wilp, A. G. and Casini, R. and Carille, A. and Lecinski, A. R. and Sewell, S. and Zmarzly, P. and Eigenbrot, A. D. and Beck, C. and Wager, F. and Kuölker, M. 2022

LEADERSHIP

Lead design, commissioning, and operation of largest production line at GE/Suez/Veolia Analytical Instruments in Boulder, CO
 Lead engineer for multiple UCAR/NCAR projects in Boulder, CO: ChroMag. <u>Guyonis</u>, KSO Lyop, filter

Experience

- ENGINEER III | UCAR/NCAR/HAO | 2018-CURRENT · Mechanical and electrical design of scientific instruments, Beckhoff [https://gar.and LabView programming · Thermodynamic and structural analysis of instruments. FEA in SolidWorks Simulation in addition to non-FEA calculations · Engineer in charge of mechanical and electrical integrations of the USB_instrument into the DKIST observatory
- Control system tuning, or unchanged and recursal meghatons of the Good system tuning of optical component stress.
 Basic optical engineering, such as alignments and mechanical tolerance analysis <u>affects</u> on system <u>performance</u>
 Lead Mechanical Engineer and point of contact for High Altitude Balloon instrument (DIMS)

AUTOMATION ENGINEER | GE & SUEZ | 2015-2018, CURRENT CONTRACT WORK

- ADTOWNTHON EXAMPLER [US & SOLD [2013-2013, UNKENT CONTRACT WORK > Project management and design of new production line and new product launch > PLC Programming: IEC 61131-3 based C in Beckhoff TwinfAR3, C# human machine interfaces in TwinfAT3 Industrial networking with Ethernet IP. EtherGAT and ModfBug. Sensor monitoring solutions through GE [LSight > Mechanical, electrical, and fluid design. Thermodynamic and structural analysis of production systems, ceramic structures, and frames. > FEA in SolidWorks Simulation. Contract work for PLCs programming and water systems
- GRADUATE RESEARCH ASSISTANT | GEORGIA TECH | 2013-2015
- Researcher for Ford Motor Company on sustainability and water issues in manufacturing
 Examining effect of manufacturing types, water reporting, and environmental issues
- MECHANICAL ENGINEER II | DEMATIC AG | 2011-2013
- Hired as Engineer I, received promotion to Engineer II Design of new products, iLogic automation, FEA Structural Analysis, manufacturing planning, and system integration Responsible for top level and component level design of various products, specifically the release of model UL1200

Andrew lorle X

9. Any changes to analytical models following submittal of deliverable shall be submitted to NASA as soon as practical. Scope and timing of changes may impact review and certification for flight. Not applicable.

10. Triplate Analysis Requested April 2024

Request email, from Justin Marsh:

Marsh, Justin L. (WFF-820.0)[PERATON INC]

Wed, Apr 24, 7:46 AM (6 days ago)

to me, Qian

Andrew,

The structural review team asked that I do an independent analysis of the trapeze for all load cases. I've finished with that and it shows good margins. They're requesting that you perform a similar analysis to verify my results. I believe they'll ask for this to be presented at the final PIR as a way to allow us to certify the gondola for flight in FY25.

Thanks,

Justin

Narrative on Trapeze Analysis from HAO (Andrew Carlile):

This analysis doesn't consider any of the antennae specific loads and combines those antennae loads with the total mass. The tri-plate is aluminum, so it is the softest part in the entire assembly and it's bending will affect the load paths. This model is a simple check to be compared with Justin's results with similar assumptions.

48.0





8G Vertical (DIRECT LOAD)

- Force = 33,600lbf
 - 4,200lbs below trapeze
- **Inertial Relief**
 - Equal force distribution at bottom of trapeze
- Tri-Plate Rigid

SAP Reported Material Properties

- Fty = 750 Mpa = 108.8 ksi
- Ftu = 1,000 Mpa = 145.0 ksi Carlile reports: Fty = 435 Mpa / Ftu = 670 Mpa

FEA Material Properties

- Fty = 460 Mpa = 66.7 ksi
- Ftu = 731 Mpa = 106.0 ksi

Margins

- σ max = 37.4 ksi
- Msy = 0.35
- Msu = 0.86



From HAO:



Trapeze 4gA Case From Justin:



From HAO:

Setup of remote load:

Assembly Layout Sketch Markup Evaluate SOLIDWORKS Add-Ins Simulation		₽ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$		88-52
	 HiWind Just Trapeze 			×
				×
Kemote Loads/mass				1
				E
iype spirt				G
Message ^ ^				
In case of regin connection, motion of each node within the connection region is dictate by translation and rotation of the remote point. Also the connection region will not deform. Distributed Connection allows the remote point constrained to translate and rotate with average motion of nodes within the connection region.				e e
Selection				
Rex-1-0FE-222: 99/20304 (Top Fram Attomet Range):ess Copy-6 A Fex-2-0FE-222: 99/20304 (Top Fram Attomet Range):ess Copy-7 Fex-2-0FE-222: 99/20304 (Top Fram Attomet Range):ess Copy-7 Fex-2-0FE-222: 99/20304 (Top Fram Attomet Range):ess Copy-8 Fex-2-0FE-222: 99/20304 (Top Fram Attomet Range):ess Copy-8 Fex-2-0FE-222: 99/20304 (Top Fram Attomet Range):ess Copy-8 Fex-2-0FE-222: 99/20304 (Top Fram Attomet Range):ess Copy-8			7	
Reference Coordinate System		HIP ST		
O Global		1		
User defined				
Coordinate system1				
Location		APPLY I GOV		
mm ···································				
J# 0				
₫. 0 v				
åt 0 ~			X-Location	(mm): 0
Translational Components			Y-Location	(mm): 0
N v mm v			2-LBCaBON	(mm): 0
24 🛨 🚹 37365.075 ~ 🍫			Force - Ve	Direction (N): 37,365,075
1. 1 1 37365.075 V			Force - Z-	Direction (N): 52,842.2
27 1 Is 32842.2 · · · ·		ALC: I		~
Rotational Components ~				
Connection Type				
Distributed ORigid				
Weighting Factor: Default (Constant)	2			
Mass	×			
Symbol Settinas	1 N 1			
		ALL MARKED	III ALION	



Trapeze 4gB Case From Justin:



From HAO:



Trapeze 4gC Case From Justin:



From HAO:

